

Robotics in crop farming - pest monitoring approaches using machine learning and machine vision techniques

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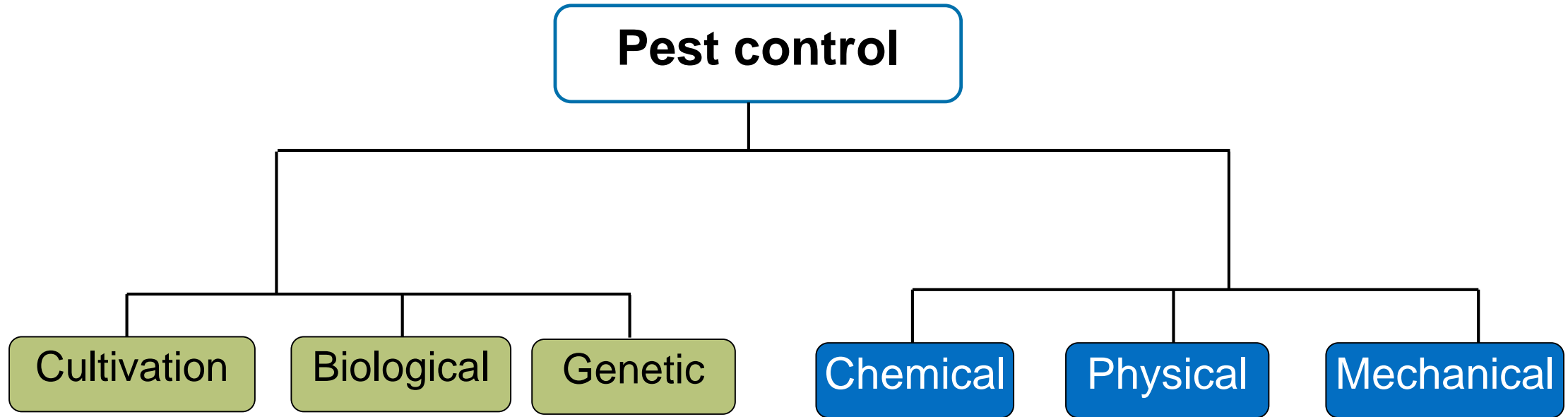
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Insect pests

- Feed on crops
- Reduce yield
- Transmit plant viruses
- ...





Collecting machine



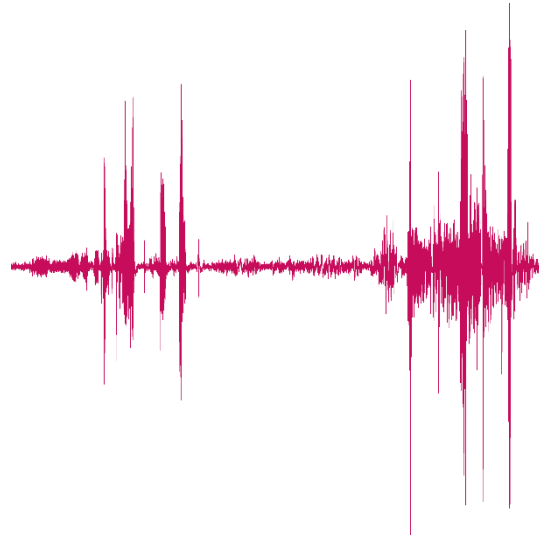
Colorado Beetle Catcher (FieldWorkers)

Collecting machine

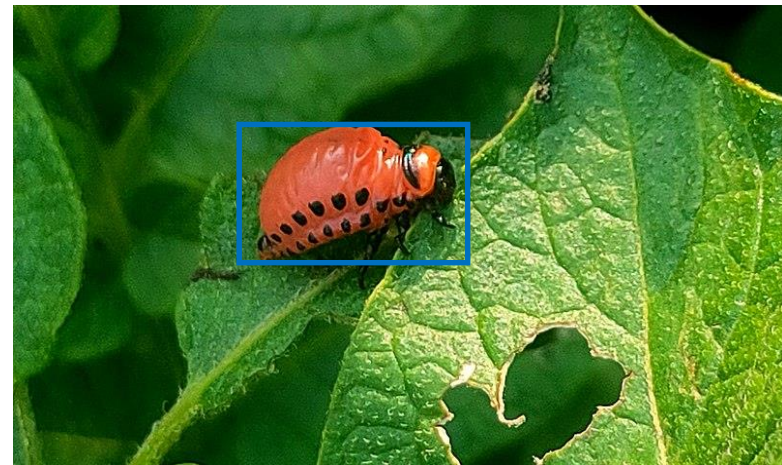
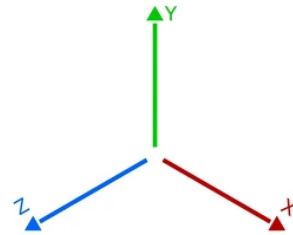
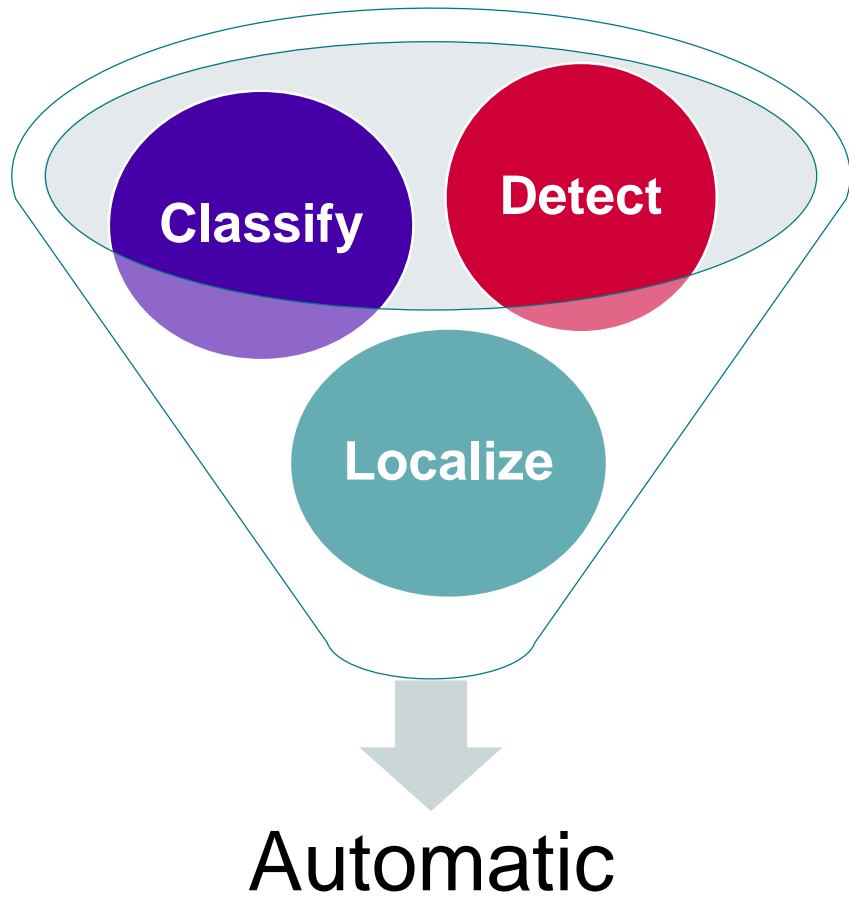


Digital tools

- Traps with camera or microphones
- Pest data
- Population



Smart system



Digitalization- robot

- Collect pest insects
- Autonomous



Perception

Control

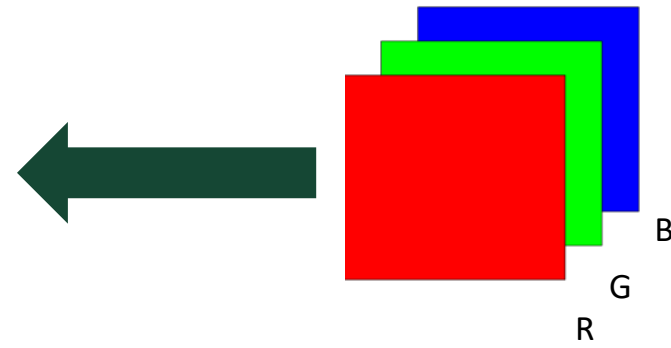
Actuator

Robot- slug control

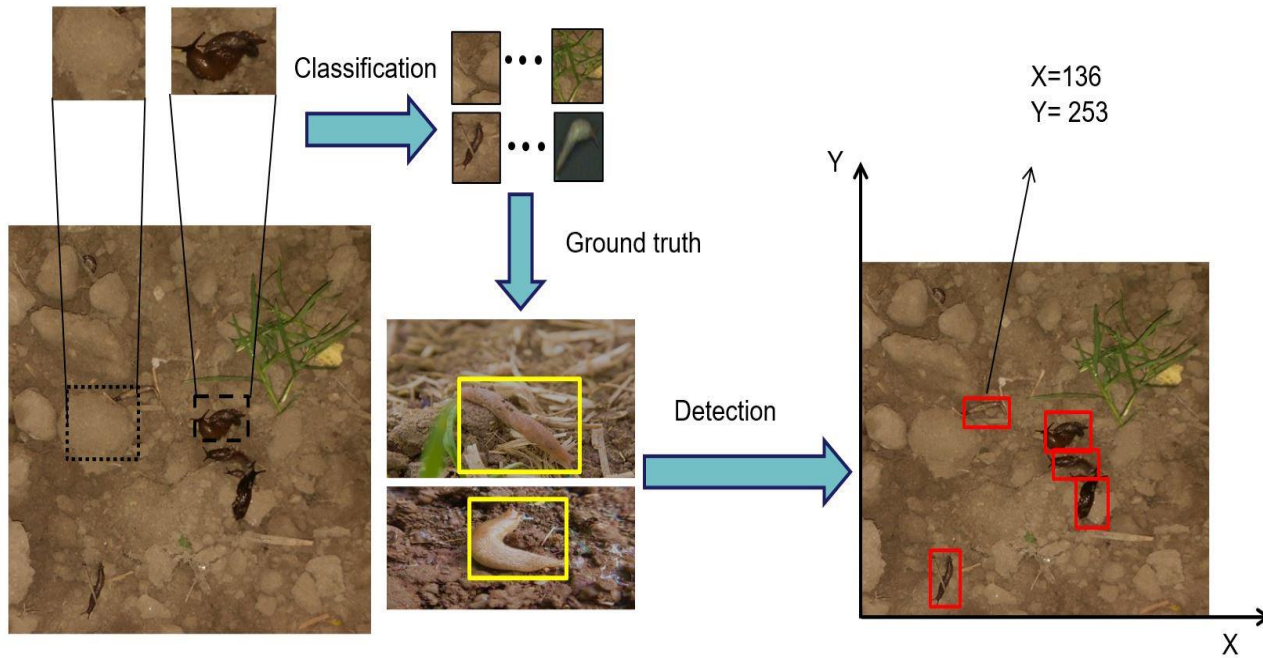
- ✓ Slug pellets
- ❖ Harm beneficials
- ❖ Fail due to weather conditions



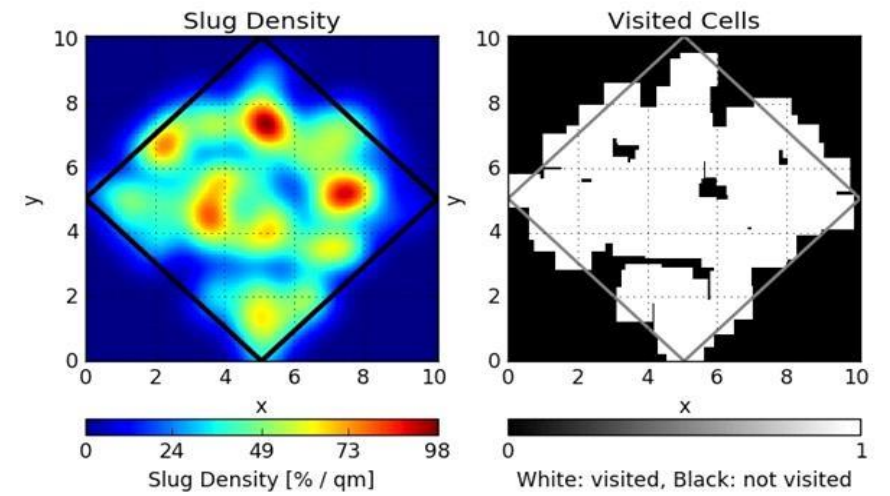
Slug detection



Slug detection



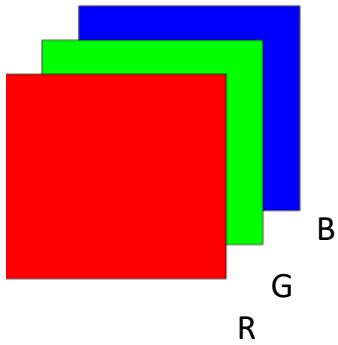
Deep learning



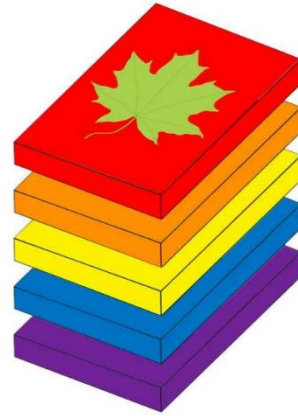
Slug detection



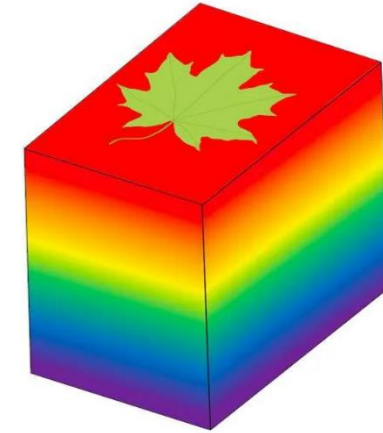
Optical techniques



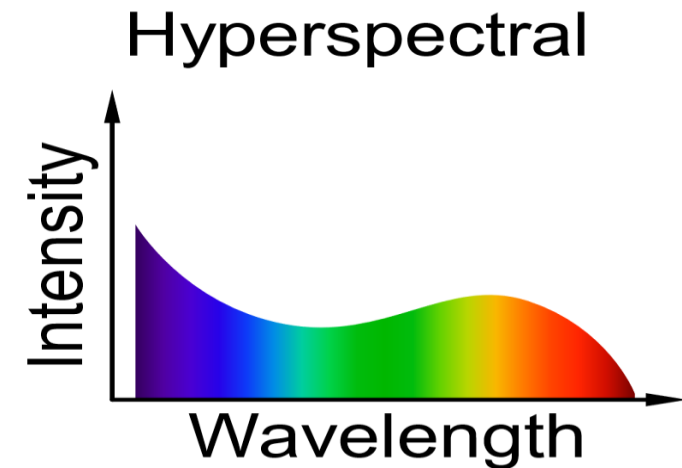
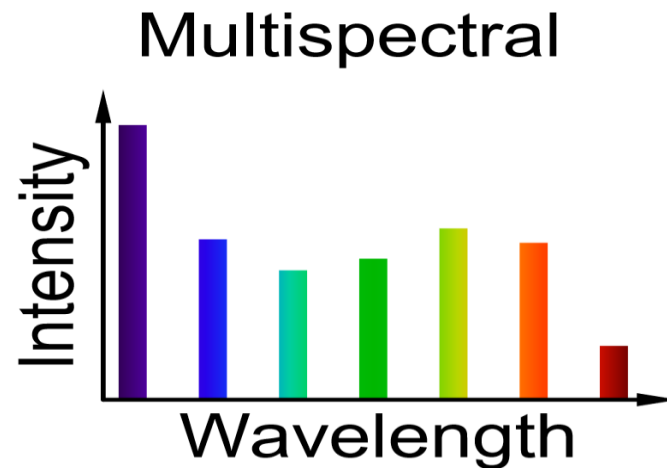
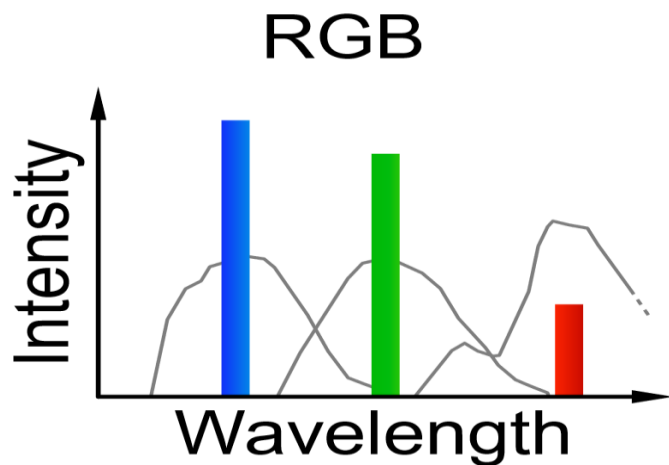
Colour image



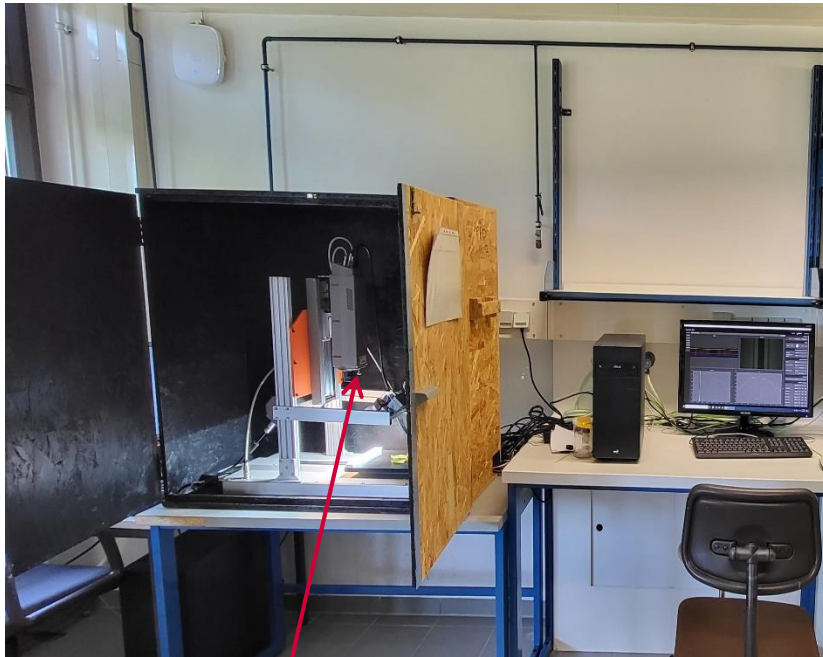
Multispectral



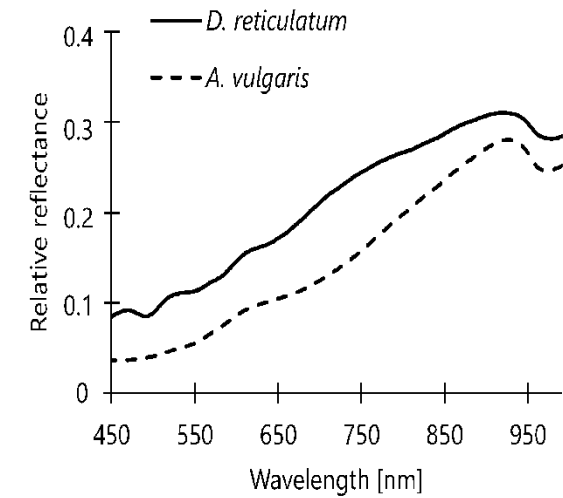
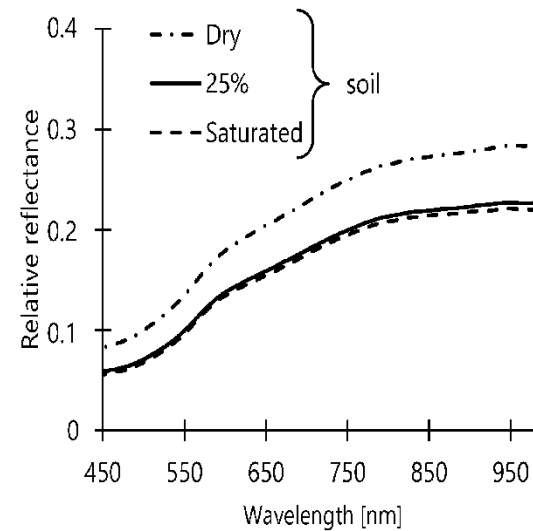
Hyperspectral



Band selection



Vis-NIR (396–1010 nm)



Change filter

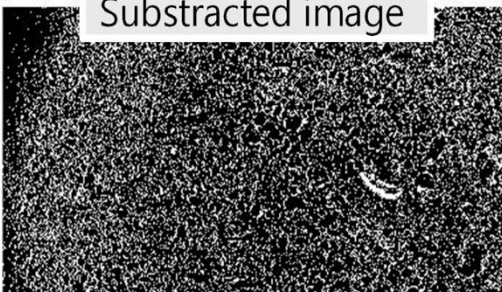
925 nm



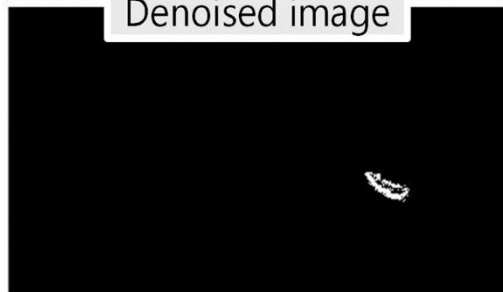
975 nm



Substracted image



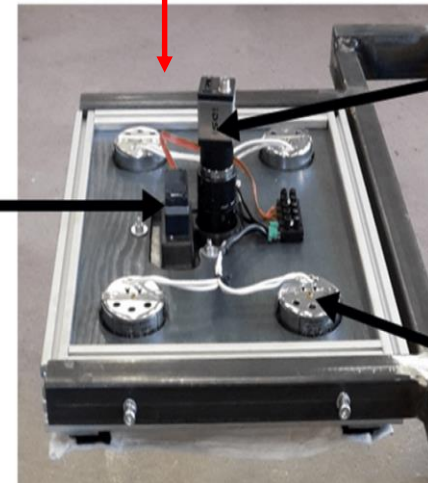
Denoised image



Narrow bandpass filters



Servo of filter changer



Camera

Halogen lights

Slugs over crops

- Depth and colour images (perception and localization)
- Finding x,y,z coordinates (location of slugs)

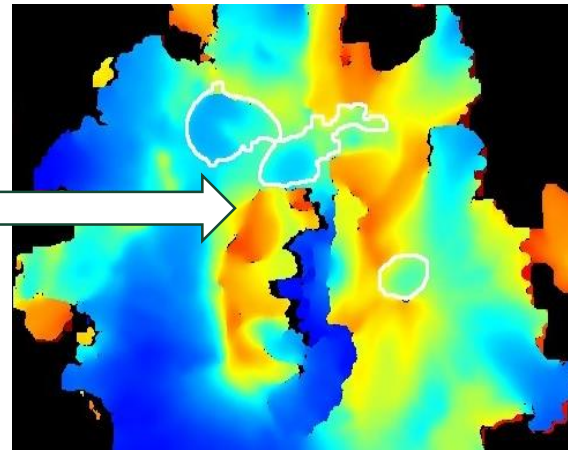


Slugs over crops

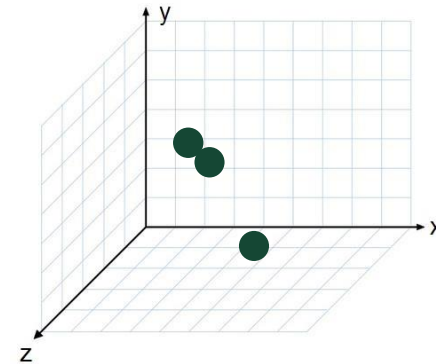
- Machine learning/image analysis → slug detection



Detect



Distance



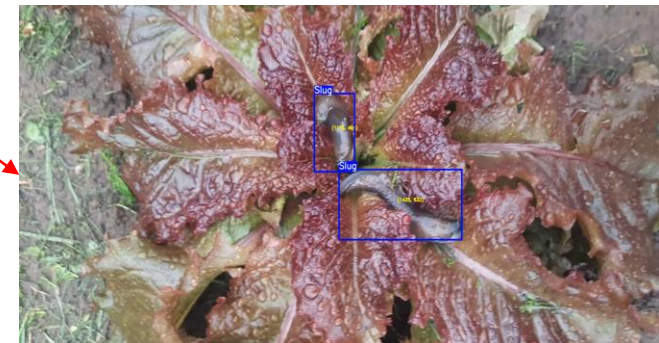
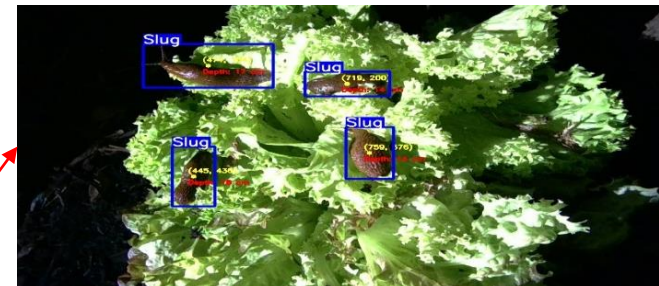
Object detection



Deep Learning



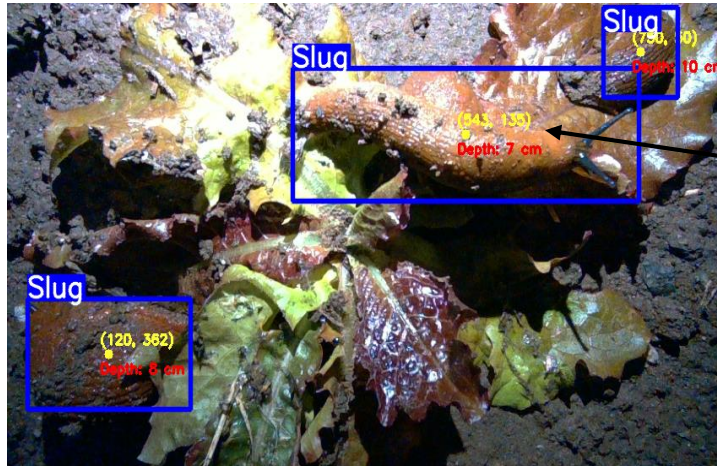
Night-time



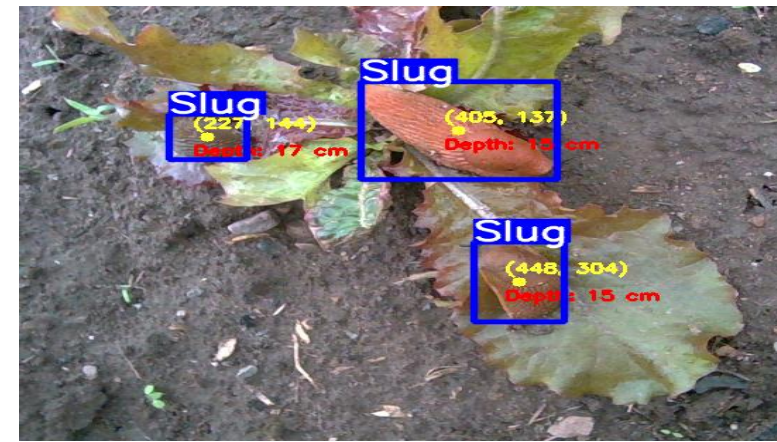
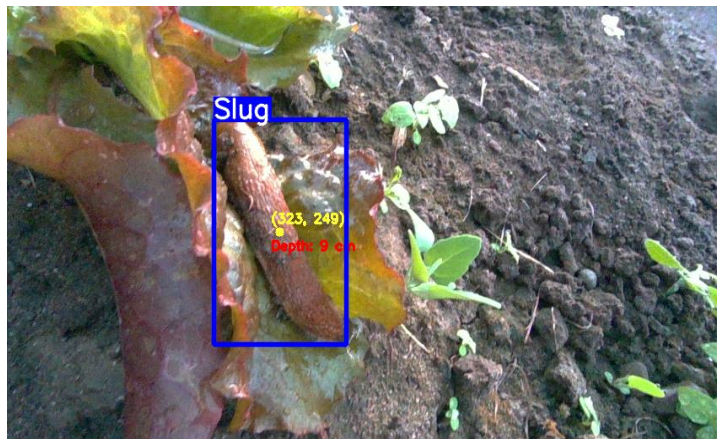
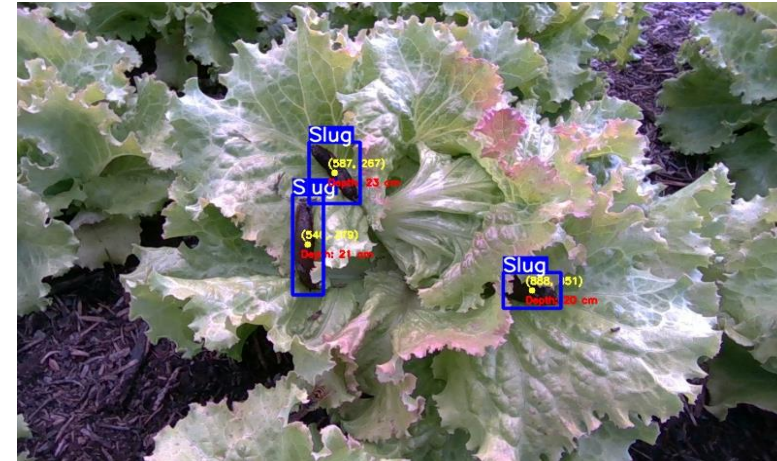
Day-time



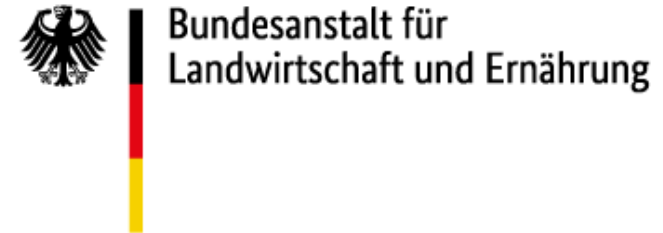
Slug detection (x,y,z)



x, y, z



Detection of slugs in complex situations



Projects: MsrBot, DigiPlus, MORE-bot

Thank you for your attention



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Reference

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